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A Balloon Model Examination with Impulsion of Cu-Nanoparticles as Drug Agent through Stenosed Tapered Elastic Artery

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ABSTRACT

In this speculative examination, main focused is to address Cu-nanoparticles application in an inclined stenosed elastic artery with balloon model examination. Flow of blood in an inclined stenotic artery is investigated mathematically by considering its behavior as viscous fluid. The dimensionless terms of temperature, velocity, resistance to blood flow and stress on wall of stenotic inclined artery has been computed by using mild stenosis approximation. The model is also used to understand the significance of overlapping stenosed artery with tapered angle and inclination angle. At the end, the results confirmed that the impulsion of copper as drug agent minimized the amplitude of the resistance to blood flow and hence nanoparticles plays an important role in engineering as well in biomedical applications.

Keywords: Blood flow; Overlapping stenosis; Balloon model; Cu-Nanoparticles.

NOMENCLATURE

e _o F	normal artery radius rate of flow	u_{0}	averaged velocity
Gr h(z) k L LO p Ren r, z Srz t To, T1	Grashof number stenosis height thermal conductivity artery length length of stenosis pressure force Reynolds number radial and axial directions stress on wall time temperature considered on walls	$egin{array}{c} \omega & & & & & & & & & & & & & & & & & & $	angular frequency density heat capacitance height of stenosis heat source parameter nanoparticle volume fraction nano dimensionless temperature position of stenosis resistance to blood shape parameter thermal expansion

1. INTRODUCTION

Atherosclerosis is a syndrome of arteries which involve complex interactions between blood flow and the artery wall. Hemodynamics factors, such as resistance impedance to flow and wall shear stress plays very important role in keeping normal vascular endothelial function which is directly associated to the generation and propagation of the atherosclerotic lesion. The higher resistance to flow can also become

progressively important as the stenosis becomes more severe. The development of stenosis causes to block circulation of blood in the heart which may result numerous cardiovascular diseases such as angina, myocardial infarction etc. The actual reason for growth of stenosis in an artery is not known, but its impact on the flow features has been considered by many researchers i.e., Texon (1957), Young *et al.* (1973), Liu and Tang (2000), Mandal *et al.* (2011), Nadeem and Ijaz (2016).

Several investigates about stenotic growth indicate that the studies are mostly concerned with the particular stenosis while the stenosis may progress in the sequence or may be of asymmetrical shapes or of composite or overlapping in nature. Chakravarty et al. (1996) explored mathematical problem related to blood flow through tapered wall segments. They considered non-linear and two-dimensional blood flow mathematical model in stenotic arteries with the accumulation of overlapped stenosis. Mekheimer et al. (2008) explored theoretical model of an elastic stenosed artery. They discussed here the impact of induced magnetic field on flow of blood. Ismail et al. (2008) explored non-newtonian model of blood with an elastic stenosed artery. Mekheimer et al. (2012) deliberated the behavior of blood flow through anisotropically tapered stenosed artery in presence of heat and chemical reactions. They treated here nature of blood in arteries as non-newtonian micropolar fluid

In recent study of medicine, with the advancement of coronary balloon angioplasty, there has been a significant increase in the use of catheters of several sizes to minimize the stenotic effects. The insertion of a catheter in a blood vessel will change the flow field. Dash et al. (1996) explored pattern of blood in stenotic arteries. They found here that resistance increases due to catheterization. Mekheimer et al. (2010) explored the analysis of a dusty model for the axis-symmetric flow of blood through coaxial tubes. Verma et al. (2011) deliberated mathematical problem of artery catheterization by assuming symmetric stenosis with blood flow model. For further analysis see references Sankar and Hemalatha (2007), Srivastava and Srivastava (2009), Mekheimer et al. (2012).

Theoretical models with arteries carrying blood that are cited above were considered to being horizontal however it is well known that in numerous investigation all vessels in physiological systems are not horizontal because some have inclination to the axis. Chakraborty et al. (2011) explored the mathematical model of an inclined artery by considering radially symmetric stenosis. They discussed the slip at stenotic wall, hematocrit and inclination of the artery. Mekheimer et al. (2015) examined the theoretical analysis of inclined catheterized arteries with balloon angioplasty. To discuss this analysis, here they considered blood in arteries as Carreau fluid. For some further important studies in this direction are given in Prasad et al. (2008), Mohan et al. (2013).

In engineering and medical sciences nanofluid keeps several unique features. Nanofluid enhances thermal conductivity of the considered base fluid immensely, which are stable and have no further problems such as erosion and sedimentation. Recent, study has revealed that they are important for improving the heat transport and thermal conductivity properties of the base fluid and may have potential applications in the field of biomedicine. In fact, Choi (1995) was the first who presented the experimental measurements and thermal conductivity enhancement for the thermal conductivity of nanofluids. Later on some

other investigators explored different mathematical nano models cited as Buongiorno (2005), Nadeem and Ijaz (2015). Ellahi et al. (2014) explored the nonnewtonian mathematical model of nanofluid with tapered stenotic artery. Nadeem and Ijaz (2015) explored nanoparticles examination through stenotic artery with permeable walls. They deliberated here solid nanoparticles consequence of a curved stenotic artery. Nadeem and Ijaz (2016) explored the nanoparticles possessions by considering mathematical nano blood flow models. They concluded that impact of hemodynamics of a stenotic artery minimizes by introducing nanoparticles. Some more useful analysis is given in the references Jiang et al. (2007), Gentile et al. (2007), Akbarzadeh et al. (2016).

With the above theoretical inspirations, an inclined vessel with overlapped stenotic region is considered in this examination. The catheterization effect with help of balloon model is also assumed. The dimensional governing equations are simplified after using mild stenosis approximation. After this approximation differential equation are solved by using exact technique. The acquired effects of hemodynamics have been deliberated for various parameters with the help of graphical illustration. At the end of this investigation, we note that use of nanoparticles as drug agent minimizes the hemodynamics of stenotic artery.

2. FORMULATION OF THE PROBLEM

To proceed this analysis, unsteady, incompressible and viscous nanofluid is considered that flows through a stenotic artery of finite length L. Also to discuss the nano effects heat transfer existence is introduced by considering temperature T_0 at the inner wall of balloon and temperature T_1 at the wall of stenotic artery. The configuration of stenotic segment is defined as [6]

$$\bar{h}(z,t) = \left[(a*z + e_0) - \frac{\delta * \cos \phi}{L_0} (\bar{z} - e^*) \{ 11 - \frac{94}{3L_0} (\bar{z} - e^*) + \frac{32}{L_0^2} (\bar{z} - e^*)^2 - \frac{32}{3L_0^2} (\bar{z} - e^*)^3 \} \right]$$

$$x_1(t), \qquad e^* \le \bar{z} \le e^* + \frac{3}{2L_0}$$

$$= (a*\bar{z} + e_0)x_1(t) \qquad \text{otherwise,}$$
(1)

in above $\overline{h}(z,t)$ is the stenotic radius, e_0 is the non-stenotic radius, ϕ is the tapered angle, $\delta\cos\varphi$ is critical height of the stenotic segment, $\frac{3}{2L_0}$ is the length, e^* is position and e^* =tan φ is the slope of the stenotic vessel. Different possible shapes of artery are analyzed by considering φ <0 for convergent shape, ϕ =0for non-tapered shape and φ >0for divergent shape. The time-variant parameter is defined as

$$x_1(t) = 1 - c(\cos wt - 1)\exp[-cwt],$$
 (2)

where c is defined as constant, W as the angular frequency and t as time. Balloon model is defined as

$$\overline{H}(z) = e_0 \{ k + \delta_1 \exp[-\pi^2 (z - z_d - 0.5)^2] \}, \quad e^* \le \overline{z} \le e^* + \frac{3}{2L_0},$$

$$= e_0 k \quad \text{otherwise,}$$
(3)

where δ is the maximum height of balloon and is attained at $z = z_d + 0.5$, e_0k is the radius of the balloon, Z_d is the axial translation of the balloon.

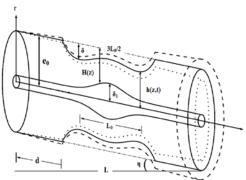


Fig. 1. Configuration of overlapped stenotic artery.

The formulated equations in the presence of nanoparticles can be written as,

$$\frac{\partial \overline{v}}{\partial r} + \frac{\overline{v}}{r} + \frac{\partial \overline{w}}{\partial \overline{z}} = 0, \tag{4}$$

$$\rho_{nf} \left(\frac{\partial \overline{v}}{\partial \overline{t}} + \overline{v} \frac{\partial \overline{v}}{\partial \overline{r}} + \overline{w} \frac{\partial \overline{v}}{\partial \overline{z}} \right) = -\frac{\partial \overline{p}}{\partial \overline{r}} + \mu_{nf} \left(\frac{\partial^2 \overline{v}}{\partial r^2} + \frac{1}{r} \frac{\partial \overline{v}}{\partial \overline{r}} + \frac{1}{r} \frac{\partial \overline{v}}{\partial \overline{r}}$$

$$\rho_{nf}\left(\frac{\partial \overline{w}}{\partial \overline{t}} + v\frac{\partial \overline{w}}{\partial \overline{r}} + w\frac{\partial \overline{w}}{\partial \overline{z}}\right) = -\frac{\partial \overline{p}}{\partial \overline{z}} + \mu_{nf}\left(\frac{\partial^{2} \overline{w}}{\partial \overline{r}^{2}} + \frac{1}{r}\frac{\partial \overline{w}}{\partial \overline{r}} + \frac{1}{r}\frac{\partial \overline{w}}{\partial \overline{r}} + \frac{\partial^{2} \overline{w}}{\partial \overline{z}^{2}}\right) + g(\rho \gamma)_{nf}(\overline{T} - \overline{T}_{1})$$

$$\sin \eta,$$
(6)

$$\left(\frac{\partial \overline{T}}{\partial t} + \overline{v} \frac{\partial \overline{T}}{\partial r} + \overline{w} \frac{\partial \overline{T}}{\partial z}\right) = \frac{k_{nf}}{(\rho c_p)_{nf}} \left(\frac{\partial^2 \overline{T}}{\partial r^2} + \frac{1}{r} \frac{\partial \overline{T}}{\partial r} + G_r = \frac{g \gamma_f \rho_f e_0^2 (T_0 - T_1)}{u_0 \mu_f}, \beta = \frac{q_0 e_0^2}{(T_0 - T_1) k_f}, \beta =$$

in above equation \overline{v} and \overline{w} is the velocity components, T is the temperature, q_0 is the heat generation parameter. For the considered single nano phase model k_{nf} denotes thermal conductivity, μ_{nf} is the viscosity, ρ_{nf} is the density, $(\rho c_p)_{nf}$ is the heat capacitance, γ_{nf} is the thermal expansion coefficient and the thermo physical properties are given as (see Table (1))

Table 1 Thermophysical properties of base fluid and solid nanoparticles

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Properties	Blood	Cu					
c_p	3594	385					
ρ	1063	8933					
k	0.492	400					
γ	0.18	1.67					

$$\frac{\mu_{nf}}{\mu_{f}} = \frac{1}{(1-\Phi)^{2.5}}, \ \alpha_{nf} = \frac{k_{nf}}{(\rho c_{p})_{nf}},$$

$$\frac{\rho_{nf}}{\rho_{f}} = (1-\Phi) + \Phi \frac{\rho_{s}}{\rho_{f}},$$

$$\frac{(\rho c_{p})_{nf}}{(\rho c_{p})_{f}} = (1-\Phi) + \frac{(\rho c_{p})_{s}}{(\rho c_{p})_{f}} \Phi,$$

$$\frac{(\rho \gamma)_{nf}}{(\rho \gamma)_{f}} = (1-\Phi) + \frac{(\rho \gamma)_{s}}{(\rho \gamma)_{f}} \Phi,$$

$$k_{nf} = k_{f} \left[\frac{(k_{s} + 2k_{f}) - 2\Phi(k_{f} - k_{s})}{(k_{s} + 2k_{f}) + \Phi(k_{f} - k_{s})} \right],$$
(8)

where ρ_f denotes the density, μ_f is the viscosity, γ_f is thermal expansion coefficient, $(\rho c_p)_f$ is the heat capacitance and k_f is thermal conductivity of considered base fluid, while ρ_s denotes the density, γ_s is the thermal expansion coefficient, $(\rho c_p)_s$ is the heat capacitance, Φ is the nanoparticle volume fraction and k_s is the thermal conductivity of the considered solid nanoparticles. Non dimensional parameters are defined as,

$$\frac{\partial^{2} \overline{w}}{\partial z^{2}} + g(\rho \gamma)_{nf}(\overline{T} - \overline{T}_{1}) \qquad r = \frac{\overline{r}}{e_{0}}, z = \frac{\overline{z}}{L_{0}}, w = \frac{\overline{w}}{u_{o}}, v = \frac{L_{0} \overline{v}}{u_{o} \delta}, \\
\sin \eta, \qquad p = \frac{e_{0}^{2} \overline{p}}{u_{o} L_{0} \mu_{f}}, t = \frac{\overline{t} u_{o}}{L_{0}}, R_{en} = \frac{e_{0} u_{o} \rho_{f}}{\mu_{f}}, \\
\frac{k_{nf}}{(\rho c_{p})_{nf}} (\frac{\partial^{2} \overline{T}}{\partial \overline{r}^{2}} + \frac{1}{\overline{r}} \frac{\partial \overline{T}}{\partial \overline{r}} + G_{r} = \frac{g \gamma_{f} \rho_{f} e_{0}^{2} (T_{0} - T_{1})}{u_{0} \mu_{f}}, \beta = \frac{q_{0} e_{0}^{2}}{(T_{0} - T_{1}) k_{f}}, \\
\frac{\partial^{2} \overline{T}}{\partial \overline{z}^{2}} + \frac{q_{0}}{(\rho c_{p})_{nf}}, \qquad \theta = \frac{T - T_{1}}{T_{0} - T_{1}}.$$
(9)

Where in above equation R_{pn} denotes the Reynolds

number, G_r is the Grashof number, β is the heat source parameter and u_0 is the averaged velocity. By mean of Eq. (9) and considered approximations (mild stenosis $\delta^* = \frac{\delta}{e_0} \prec \prec 1$ and $\varepsilon = \frac{e_0}{b} \approx O(1)$), the formulated Eqs. (5) to (7) can be reduced as

$$\frac{\partial p}{\partial r} = 0,\tag{10}$$

$$\frac{\partial p}{\partial z}(1-\Phi)^{2.5} =$$

$$\frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + (1 - \Phi)^2 \cdot \frac{(\rho \gamma) \eta f}{(\rho \gamma) f} \sigma_4 \theta, \tag{11}$$

$$\frac{\partial^2 \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} + \beta \sigma_2 \sigma_3 = 0, \tag{12}$$

where

$$\sigma_{1} = (1 - \Phi) + \Phi \frac{(\boldsymbol{\alpha}_{p})_{s}}{(\boldsymbol{\alpha}_{p})_{f}}, \ \sigma_{2} = \frac{1}{\sigma_{1}},$$

$$\sigma_{3} = \sigma_{1} \left(\frac{(1 - \Phi)k_{s} + (\Phi + 2)k_{f}}{(2\Phi + 1)k_{s} + 2(1 - \Phi)k_{f}} \right)$$

$$\sigma_{4} = \left((1 - \Phi) + \Phi \frac{\rho_{s} \gamma_{s}}{\rho_{f} \gamma_{f}} \right) (1 - \Phi)^{2.5} G_{r} \sin \eta.$$
(13)

The geometry of arterial stenosis and balloon model in dimensionless form are defined as

$$h(z, t) = [(az+1) - \delta \cos \phi (z - \sigma^*) \{11 - \frac{94}{3}$$

$$(z - \sigma^*) + 32(z - \sigma^*)^2 - \frac{32}{3} (z - \sigma^*)^3 \}]$$

$$x_1(t), \qquad \sigma^* \le z \le \sigma^* + \frac{3}{2}$$

$$= (az+1)x_1(t) \qquad \text{otherwise,}$$

$$(14)$$

with

$$\delta = \frac{\delta^*}{e_0}, \ \sigma^* = \frac{e^*}{L_0}, \ a^* = \frac{aL_0}{e_0}.$$
 (15)

And

$$H(z) = k + \delta_1 \exp[-\pi^2 L_0^2 (z - \frac{(z_d + 0.5)}{L_0})^2], \quad \sigma^* \le z \le \sigma^* + \frac{3}{2}, \quad (16)$$

$$= k \quad \text{otherwise.}$$

Corresponding boundary conditions are defined as

$$w = 0$$
 at $r = h(z,t)$, $w = 0$ at $r = h(z,t)$,
(17)

$$\theta = 0$$
 at $r = h(z,t)$, $\theta = 1$ at $r = H(z)$. (18)

The exact solutions of Eqs. (11) and (12) using Eqs. (17) and (18) are directly written as

$$\theta = \frac{1}{4(\ln(h) - \ln(H))} (4(\ln(h) - \ln(H)) + \beta \sigma_2 \sigma_3$$

$$(h^2(\ln(r) - \ln(H)) + r^2(-\ln(h) + \ln(H)) + (\ln(h) - \ln(r))H^2)),$$
(19)

$$w = \frac{dp}{dz} \frac{(1-\Phi)^{25}}{4(\ln(h) - \ln(H))} ((H^2 - r^2) \ln(h) + (-h^2 + r^2) \ln(h) + (h^2 - H^2) \ln(r)) + \frac{1}{64(\ln(h) - \ln(H))^2} (-16((-H^2 + r^2)(\ln(h))^2 + (-h^2 + H^2) \ln(r) + (H^2 - r^2) \ln(h)(-1 + \ln(h) + \ln(r)) + \ln(h)(h^2 - r^2 + (-H^2 + r^2) \ln(r))) + \beta((3H^4 - 4H^2r^2 + r^4) (\ln(h))^2 + (3h^4 - 4h^2r^2 + r^4)(\ln(H))^2 - 4 (h^2 - H^2)^2 \ln(r) - (h^2 - H^2) \ln(H)(-4h^2 + 4r^2 + (3(h^2 + H^2) - 4r^2) \ln(r)) + \ln(h)((-3(h^4 + H^4) + 4(h^2 + H^2)r^2 - 2r^4) \ln(H) + (h^2 - H^2)(-4H^2 + 4r^2 + (3(h^2 + H^2) - 4r^2) \ln(r))))\sigma_2\sigma_3)\sigma_4).$$

$$(20)$$

Expression of flow rate is defined as

$$F = \int_{H}^{h} rwdr. \tag{21}$$

Using Eq. (20) into Eq. (21), expression of pressure gradient is given as

$$\frac{dp}{dz} = -\frac{F - A(z)}{\frac{(1 - \Phi)^{2.5}}{16} \left(h^4 - H^4 + \frac{(h^2 - H^2)^2}{-\ln(h) + \ln(H)} \right)}, (22)$$

where

$$A(z) = \frac{1}{384(\ln(h) - \ln(H))^{2}} (6(-4(h^{2} - H^{2})^{2} + (\ln(h) - \ln(H))(3h^{4} + 4h^{2}H^{2} - 7H^{4} + 4H^{4}$$

$$(-\ln(h) + \ln(H)))) + \beta(h^{2} - H^{2})(6$$

$$(h^{2} - H^{2})^{2} + (-9h^{4} + 9H^{4} + 4(h^{4} + h^{2}H^{2} + H^{4})(\ln(h) - \ln(H)))(\ln(h) - \ln(H)))\sigma_{2}\sigma_{3})\sigma_{4}.$$
(23)

Pressure drop through overlapped stenotic artery is given as

$$\Delta p = \int_{0}^{L} \left(-\frac{dp}{dz} \right) dz. \tag{24}$$

Using Eq. (24), the resistance to blood can be estimated as

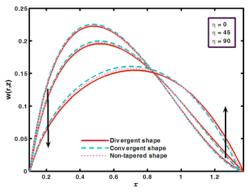


Fig. 2. Velocity profile for $\Phi = 0.01$.

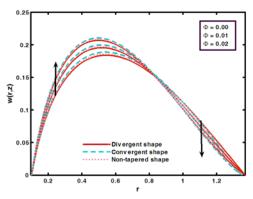


Fig. 3. Velocity profile for $\eta = 45$.

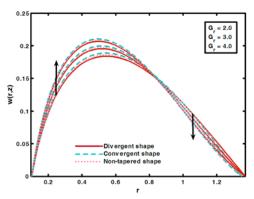


Fig. 4. Velocity profile for $\beta = 2.0$.

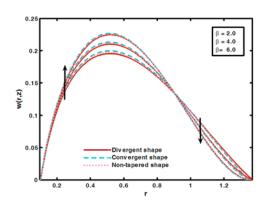


Fig. 5. Velocity profile for $G_{\Gamma} = 2.0$.

$$\lambda = \frac{\Delta p}{F} = \int_{0}^{\sigma^{*}} M(z) \big|_{h = (az+1)x_{1}(t)} dz + \int_{\sigma^{*}}^{\sigma^{*}+\frac{3}{2}} N(z) dz + \int_{\sigma^{*}+\frac{3}{2}}^{L} M(z) \big|_{h = (az+1)x_{1}(t)} dz,$$
(25)

where

$$M(z) = N(z) |_{h=(az+1)x_1(t), H=k}$$
 (26)

To evaluate the stresses on the wall of artery following expression is considered [6]

$$S_{rz} = -\frac{\mu_{nf}}{\mu_{f}} \left(\frac{\partial w}{\partial r} \right)_{r=h}.$$
 (27)

Above Eqs. (27) and (25) are further solved by using Mathematica software

3. GRAPHICAL RESULTS AND DISCUSSION

In this unit for theoretical examination figures of wall shear stress, resistance, velocity, temperature profile and streamlines are plotted with the help of physical parameters such as the Grashof number G_r , heat source parameter β , inclination angle η and nanoparticles volume fraction Φ . These

parameters are kept constant such as $\eta = 45$, $\delta = 0.01$, $\sigma^* = 0.75$, F = 0.1, t = 0.5, $G_r = 2.0$, $\omega = 7.854$, $\beta = 2.0$, $\delta_1 = 0.01$, $z_d = 0.1$, k = 0.1, Φ =0.01. The graphs of axial velocity W against r for overlapping stenosis are given in Figs. (2) to (5). The variation of inclination angle η is given in Fig. (2). It is observed from this graph that velocity starts decreasing near the wall of the balloon between the interval $H \le r \le 1.0$ (at $\eta = 90$), $H \le r \le 0.85$ (at $\eta = 0$ and n=45) and higher magnitude for convergent shape is depicted in these regions, while opposite behavior is depicted near wall of stenotic artery in the region $1.01 \le r \le h$ (at $\eta = 90$), $0.86 \le r \le h$ (at $\eta = 0$ and $\eta = 45$). Figs. (3) to (5) shows the variations for Grashof number G_r , heat source parameter β and nanoparticles volume fraction Φ on the graphs of velocity profile. It is depicted that velocity profile gives higher magnitude for convergent shape and start increasing near balloon wall of in the region $H \le r \le 0.86$, while opposite behavior is depicted near arterial wall in the region $0.87 \le r \le h$. The phenomenon of nano temperature profile is given in Figs. (6) and (7). It is depicted that the nano temperature profile increases with an increase in the values of heat source parameter β . This result is obtained due to increase in the thermal behavior of

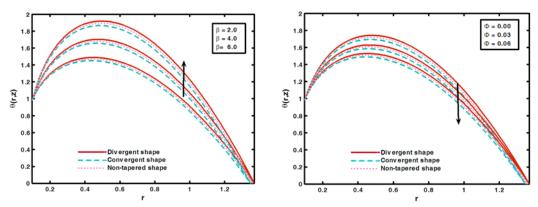
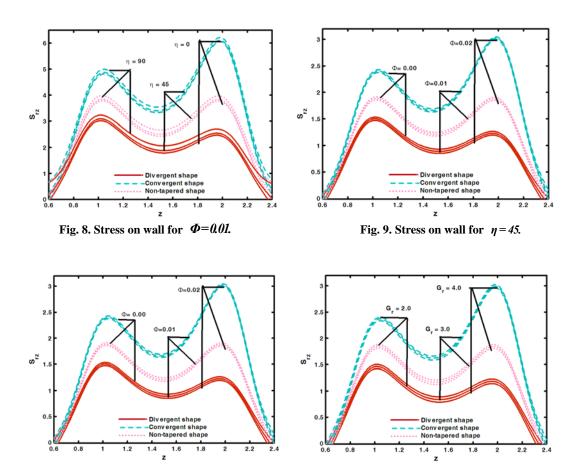


Fig. 6. Nano temperature distribution for $\Phi = 0.01$. Fig. 7. Nano temperature distribution for $\beta = 20$.

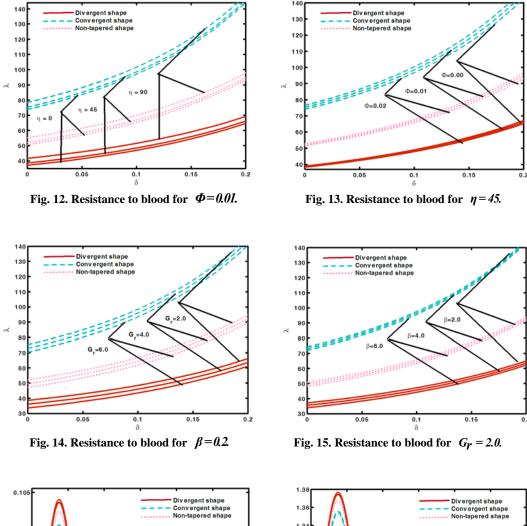


the base fluid, while decreases with an increase in the nanoparticle volume fraction. The graph of the temperature phenomena gives higher magnitude for divergent shape when compare to other shapes. Figs. (8) to (11) are plotted to understand stress behavior on wall of stenotic artery. From these graphical illustrations one may analyze that stresses on the wall of inclined stenotic artery start decreasing towards the downstream of the stenotic region and then start rapidly increasing towards the end of the inclined stenotic artery. One may also analyze from these stress patterns that convergent shape of an artery

Fig. 10. Stress on wall for $\beta = 2.0$.

gives higher magnitude when compared to other non-tapered and divergent shapes of stenotic artery. The stresses behavior for parameters inclination angle η and nanoparticles volume fraction Φ are given in Figs. (8) and (9). It is depicted under this stress pattern that with an increase in the inclination angle η stresses on wall of an inclined stenotic artery decreases, while stresses on wall decreases by increasing in the concentration of nanoparticles. Figs. (10) and (11) relates the stress with different parameters such as Grashof number G_r and heat

Fig. 11. Stress on wall for $G_r = 2.0$.



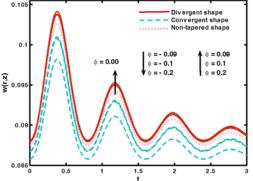


Fig. 16. Chart of velocity profile with *t*

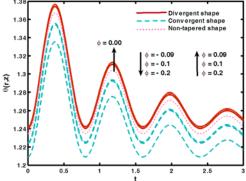
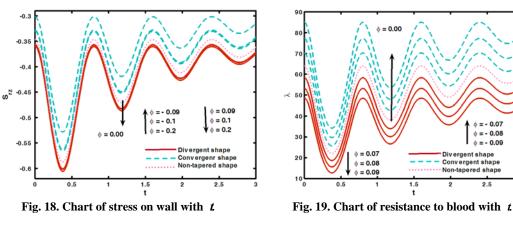
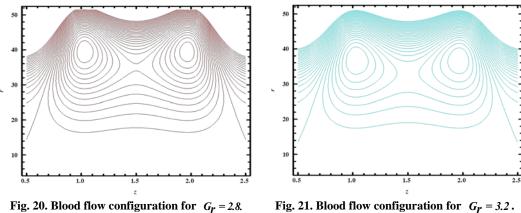


Fig. 17. Chart of temperature profile with *t*

source β . It is depicted from this pattern that the stresses on wall of stenotic inclined artery decreases with an increase in Grashof number G_r and heat source β . Figs. (12) to (15) are strategized to show the variation of resistance to flow versus the height of stenosis δ with different shape of inclined artery. It is observed that resistance to flow gives higher magnitude for convergent shape as comparing to other shapes and increases with an increase in the height of stenosis. The graphical illustration for inclination angle η and nanoparticles volume fraction Φ is given in Figs. (12) and (13). It is analyzed from

this pattern that resistance to flow increases with an increase in inclination angle η , while opposite behavior is depicted for nanoparticles volume fraction case. Fig. (14) is plotted for Grashof number G_r and noted that resistance to flow reduces with an increase in G_r . The inspiration of heat source parameter β on resistance to flow is plotted in Fig. (15). One may depict from this figure that resistance to flow minimizes with an increase in β . Figs. (16) to (19) represent the behavior of wall shear stress and resistance to blood flow against time t for almost three cyclic phases. One regular observation from





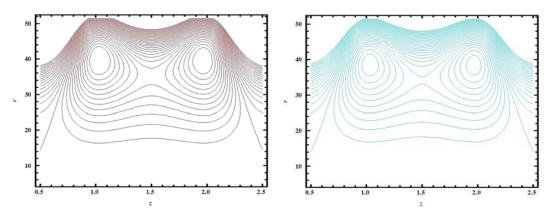
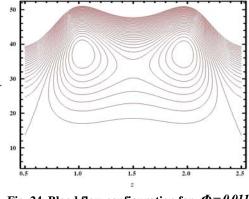


Fig. 22. Blood flow configuration for $\beta = 0.46$.

Fig. 23. Blood flow configuration $\beta = 0.50$.

these figures is that the magnitude of first cycle starts with decreasing behavior to obtain its least possible value and after this it starts increasing towards its extreme value. This similar pattern is observed for other remaining cycles. It is also analyzed that oscillated cycles decay as time t increases. This graphical result also shows that the stresses on the wall and resistance to blood flow decreases for converged stenotic inclined shape when compared to the other shapes. It is noted here that resistance to flow and stresses on wall gives higher magnitude for converged shape, while the graphical illustration of

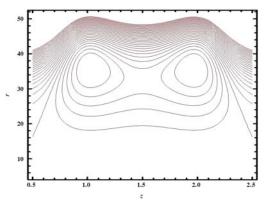
velocity and temperature profile gives higher magnitude for divergent shape. Trapping is a motivating phenomenon for to show blood flow configuration in an inclined stenotic artery and here this configuration is discussed from Figs. (20) to (29). In Figs. (20) to (23), it is depicted that number of trapping bolus decreases with an increase in G_r and β . The effects of nanoparticles volume fraction Φ are given in Figs. (24) and (25). It is noted here from this pattern that the trapping bolus decreases with an ncrease in nanoparticles volume fraction.



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Fig. 24. Blood flow configuration for $\Phi = 0.011$.

Fig. 25. Blood flow configuration for $\Phi = 0.013$.



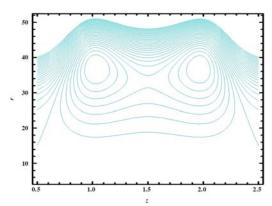
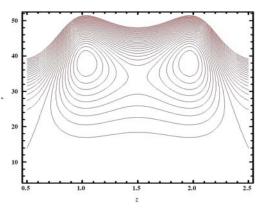


Fig. 26. Blood flow configuration for $\delta = 0.08$.

Fig. 27. Blood flow configuration for $\delta = 0.09$.



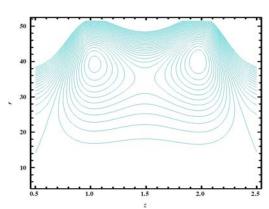


Fig. 28. Blood flow configuration for $\delta_1 = 0.00$.

Fig. 29. Blood flow configuration for $\delta_1 = 0.09$.

The trapping configuration for stenosis height δ and maximum height of balloon δ_1 are given in Figs. (26) to (29). It is depicted from this flow pattern that the number of trapping bolus increases with an increase in the values stenosis height, while trapping bolus increases in left side of inclined artery as compare to the right side of inclined artery with an increase in the values maximum height of the balloon. Table (2) is constructed to understand the numeric behavior of velocity profile for axial displacement of the balloon. One may observe from this table that the velocity profile for axial

displacement z_d increases throughout the inclined stenotic artery ($H \le r \le h$). It is also analyzed that velocity profile gives higher magnitude for convergent shape of artery when compare to other shapes

4. CONCLUSION

The nanoparticle with balloon model through inclined stenotic artery is deliberated in this theoretical examination. The significant remarks from this study can be concise as follows

Table 2 Variation of velocity profile for axial displacement of the balloon

Diverging shape			Converging shape			Non-tapered shape			
r	zd=0.00	$z_d = 0.05$	$z_d = 0.09$	$z_d = 0.00$	zd=0.05	$z_d = 0.09$	$z_d = 0.00$	$z_d = 0.05$	$z_d = 0.09$
Н	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000
0.2	0.10813	0.10840	0.10858	0.11091	0.11117	0.11135	0.10946	0.10972	0.10990
0.3	0.16063	0.16086	0.16102	0.16456	0.16479	0.16494	0.16250	0.16273	0.16289
0.4	0.18640	0.18658	0.18670	0.19071	0.19089	0.19101	0.18845	0.18863	0.18875
0.5	0.19512	0.19527	0.19537	0.19933	0.19947	0.19957	0.19713	0.19727	0.19737
0.6	0.19157	0.19170	0.19179	0.19532	0.19545	0.19553	0.19336	0.19349	0.19357
0.7	0.17873	0.17886	0.17894	0.18176	0.18189	0.18197	0.18018	0.18031	0.18039
0.8	0.15884	0.15898	0.15907	0.16093	0.16107	0.16116	0.15985	0.15998	0.16007
0.9	0.13379	0.13394	0.13404	0.13476	0.13492	0.13503	0.13426	0.13442	0.13453
1.0	0.10532	0.10549	0.10561	0.10502	0.10521	0.10534	0.10520	0.10538	0.10551
1.2	0.07514	0.07535	0.07549	0.07346	0.07368	0.07383	0.07437	0.07459	0.07473
h	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000

- Temperature phenomenon reduces for nanoparticle volume fraction, which shows that thermal conductivity of solid particles are helpful to dissipate heat.
- The hemodynamics of inclined stenotic artery give higher magnitude for the convergent shape when compare to other shapes.
- Stress on wall of stenotic inclined artery increases with an increase in inclination angle.
- Solid nanoparticle diminishes the hemodynamic effect that is experienced by blood while flowing in elastic stenosed inclined artery.
- Resistance to flow and stress on wall has same behavior versus *t* and this wavering magnitude is higher for the convergent case.

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